

Numerical Analysis (10th Edition)

Chapter 11.2, Problem 6E

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ON

Problem

- a.** Change Algorithm 11.2 to incorporate the Secant method instead of Newton's method. Use $t_0 = (\beta - \alpha)/(b - a)$ and $t_1 = t_0 + (\beta - y(t_0, b))/(b - a)$.
- b.** Repeat Exercise 4(a) and 4(c) using the Secant algorithm derived in part (a), and compare the number of iterations required for the two methods.

Reference: Algorithm 11.2



Nonlinear Shooting with Newton's Method

To approximate the solution of the nonlinear boundary-value pr

$$y'' = f(x, y, y'), \quad \text{for } a \leq x \leq b, \text{ with } y(a) = \alpha \text{ and } y(b) = \beta$$

(Note: Equations (11.10) and (11.12) are written as first-order s since TOL , maximum number of iterations M .

INPUT endpoints a, b ; boundary conditions α, β ; number of s

OUTPUT approximations $w_{i,1}$ to $y(t_1)$; $w_{i,2}$ to $y'(x)$ for each $i =$ that the maximum number of iterations was exceeded.

Step 1 Set $h = (b - a)/N$;
 $k = 1$;
 $TK = (\beta - \alpha)/(b - a)$. (Note: TK could also be

Step 2 While $(k \leq M)$ do Steps 3–10.

Step 3 Set $w_{1,0} = \alpha$;
 $w_{2,0} = TK$;
 $u_1 = 0$;
 $u_2 = 1$.

Step 4 For $i = 1, \dots, N$ do Steps 5 and 6.
(The Runge-Kutta method for systems is:

Step 5 Set $x = a + (i - 1)h$;

Step 6 Set $k_{1,1} = h w_{2,i-1}$;
 $k_{1,2} = h f(x, w_{1,i-1}, w_{2,i-1})$;
 $k_{2,1} = h(w_{2,i-1} + \frac{1}{2}k_{1,2})$;
 $k_{2,2} = h f(x + h/2, w_{1,i-1} + \frac{1}{2}k_{1,2}$

$k_{1,2} = h f(x + h/2, w_{1,i-1} + \frac{1}{2}k_{1,2}, w_{2,i-1} + \frac{1}{2}k_{2,2})$;
 $k_{1,1} = h(w_{2,i-1} + k_{2,2})$;
 $k_{1,2} = h f(x + h, w_{1,i-1} + k_{2,1}, w_{2,i-1} + k_{2,2})$;
 $w_{1,i} = w_{1,i-1} + (k_{1,1} + 2k_{2,1} + 2k_{3,1} + k_{4,1})/6$;
 $w_{2,i} = w_{2,i-1} + (k_{1,2} + 2k_{2,2} + 2k_{3,2} + k_{4,2})/6$;
 $k'_{1,1} = h f_y(x, w_{1,i-1}, w_{2,i-1})u_1$;
 $+ f_y(x, w_{1,i-1}, w_{2,i-1})u_2$];
 $k'_{1,2} = h[u_2 + \frac{1}{2}k'_{1,2}]$;
 $k'_{2,2} = h[f_y(x + h/2, w_{1,i-1}, w_{2,i-1})(u_1 + \frac{1}{2}k'_{1,1})$
 $+ f_y(x + h/2, w_{1,i-1}, w_{2,i-1})(u_2 + \frac{1}{2}k'_{1,2})$;
 $k'_{2,1} = h(u_2 + \frac{1}{2}k'_{2,1})$;
 $k'_{3,2} = h[f_y(x + h/2, w_{1,i-1}, w_{2,i-1})(u_1 + \frac{1}{2}k'_{1,1})$
 $+ f_y(x + h/2, w_{1,i-1}, w_{2,i-1})(u_2 + \frac{1}{2}k'_{1,2})$;
 $k'_{3,1} = h(u_1 + k'_{3,1})$;
 $k'_{4,2} = h[f_y(x + h, w_{1,i-1}, w_{2,i-1})(u_1 + k'_{1,1})$
 $+ f_y(x + h, w_{1,i-1}, w_{2,i-1})(u_2 + k'_{1,2})$];
 $u_1 = u_1 + \frac{1}{2}[k'_{1,1} + 2k'_{2,1} + 2k'_{3,1} + k'_{4,1}]$;
 $u_2 = u_2 + \frac{1}{2}[k'_{1,2} + 2k'_{2,2} + 2k'_{3,2} + k'_{4,2}]$;

Step 7 If $|w_{1,N} - \beta| \leq TOL$, then do Steps 8 and 9.

Step 8 For $i = 0, 1, \dots, N$
set $x = a + ih$;
OUTPUT $(x, w_{1,i}, w_{2,i})$.

Step 9 (The procedure is complete.)
STOP.

Step 10 Set $TK = TK - \frac{w_{1,N} - \beta}{u_1}$;
(Newton's method is used to compute TK .)
 $k = k + 1$.

Step 11 OUTPUT ("Maximum number of iterations exceeded")
(The procedure was unsuccessful.)
STOP.

Reference: Exercise 4(a)

- a.** $y'' = y^3 - yy'$, $1 \leq x \leq 2$, $y(1) = \frac{1}{2}$, $y(2) = \frac{1}{2}$; use $h = 0.1$; actual solution $y(x) = (x + 1)^{-1}$.

Reference: Exercise 4(c)

- c.** $y'' = y^2 + 2y - \ln y^3 - x^{-1}$, $2 \leq x \leq 3$, $y(2) = \frac{1}{2} + \ln 2$, $y(3) = \frac{1}{2} + \ln 3$; use $h = 0.1$; actual solution $y(x) = x^{-1} + \ln x$.

Step-by-step solution

Step 1 of 22

(a)

Write the nonlinear boundary value problem $y'' = f(x, y, y')$, $a \leq x \leq b$ with boundary conditions $y(a) = \alpha$ and $y(b) = \beta$.

The modified Nonlinear Shooting algorithm to incorporate the secant method with

$t_0 = (\beta - \alpha)/(b - a)$ and $t_i = t_0 + (\beta - y(t_0, b))/(b - a)$ is as follows:

INPUT endpoints a, b ; boundary conditions α, β ; number of subintervals $N \geq 2$;

Tolerance TOL ; maximum number of iterations M .

OUTPUT approximations $w_{i,1}$ to $y(t_1)$; $w_{i,2}$ to $y'(x)$ for each $i = 0, 1, 2, \dots, N$ or a message that the maximum number of iterations was exceeded.

$h = (b - a)/N$;

Step1 Set $k = 2$;
 $TK = (\beta - \alpha)/(b - a)$.

Step2 Set $w_{1,0} = \alpha$;
 $w_{2,0} = TK$.

Step3 For $i = 1, 2, \dots, N$ perform Steps 4 to 7.

Step4 Set $x = a + (i - 1)h$;
 $k_{1,1} = h \cdot w_{2,i-1}$;
 $k_{1,2} = h \cdot f(x, w_{1,i-1}, w_{2,i-1})$;

Step5 Set $k_{2,1} = h \cdot w_{2,i-1} + \frac{k_{1,2}}{2}$;
 $k_{2,2} = h \cdot f\left(x + \frac{h}{2}, w_{1,i-1} + \frac{k_{1,1}}{2}, w_{2,i-1} + \frac{k_{1,2}}{2}\right)$.

[Comment](#)

Step 2 of 22

Continuation of the algorithm:

$k_{3,1} = h \cdot w_{2,i-1} + \frac{k_{2,2}}{2}$;
 $k_{3,2} = h \cdot f\left(x + \frac{h}{2}, w_{1,i-1} + \frac{k_{2,1}}{2}, w_{2,i-1} + \frac{k_{2,2}}{2}\right)$;

Step6 Set $k_{4,1} = h \cdot w_{2,i-1} + \frac{k_{3,2}}{2}$;
 $k_{4,2} = h \cdot f\left(x + \frac{h}{2}, w_{1,i-1} + \frac{k_{3,1}}{2}, w_{2,i-1} + \frac{k_{3,2}}{2}\right)$.

$w_{1,i} = w_{1,i-1} + \frac{1}{6}(k_{1,1} + 2 \cdot k_{2,1} + 2 \cdot k_{3,1} + k_{4,1})$;
 $w_{2,i} = w_{2,i-1} + \frac{1}{6}(k_{1,2} + 2 \cdot k_{2,2} + 2 \cdot k_{3,2} + k_{4,2})$.

Step7 Set $TK2 = TK1 + \frac{(\beta - w_{1,N})}{(b - a)}$.

Step8 Set $TK2 = TK1 + \frac{(\beta - w_{1,N})}{(b - a)}$.

Step9 while $(k \leq M)$ perform Steps 10 to 17

Step10 Set $w_{2,0} = TK2$;
 $HOLD = w_{1,N}$.

[Comment](#)

Step 3 of 22

Continuation of the algorithm:

Step11 For $i = 1, 2, 3, \dots, N$ perform Steps 12 to 15

Step12 Set $x = a + (i - 1)h$;
 $k_{1,1} = h \cdot w_{2,i-1}$;
 $k_{1,2} = h \cdot f(x, w_{1,i-1}, w_{2,i-1})$;

Step13 Set $k_{2,1} = h \cdot w_{2,i-1} + \frac{k_{1,2}}{2}$;
 $k_{2,2} = h \cdot f\left(x + \frac{h}{2}, w_{1,i-1} + \frac{k_{1,1}}{2}, w_{2,i-1} + \frac{k_{1,2}}{2}\right)$;

$k_{3,1} = h \cdot w_{2,i-1} + \frac{k_{2,2}}{2}$;
 $k_{3,2} = h \cdot f\left(x + \frac{h}{2}, w_{1,i-1} + \frac{k_{2,1}}{2}, w_{2,i-1} + \frac{k_{2,2}}{2}\right)$;

Step14 Set $k_{4,1} = h \cdot w_{2,i-1} + \frac{k_{3,2}}{2}$;
 $k_{4,2} = h \cdot f\left(x + \frac{h}{2}, w_{1,i-1} + \frac{k_{3,1}}{2}, w_{2,i-1} + \frac{k_{3,2}}{2}\right)$.

[Comment](#)

Step 4 of 22

Continuation of the algorithm:

$w_{1,i} = w_{1,i-1} + \frac{1}{6}(k_{1,1} + 2 \cdot k_{2,1} + 2 \cdot k_{3,1} + k_{4,1})$;

Step15 Set $w_{2,i} = w_{2,i-1} + \frac{1}{6}(k_{1,2} + 2 \cdot k_{2,2} + 2 \cdot k_{3,2} + k_{4,2})$.

Step16 If $|w_{1,N} - \beta| \leq TOL$, then perform Steps 17 and 18

Step17 If $i = 0, 1, 2, \dots, N$ then set $x = a + i \cdot h$;

OUTPUT $(x, w_{1,i}, w_{2,i})$.

Step18 STOP.

$TK = TK2 - \frac{(w_{1,N} - \beta) \cdot (TK2 - TK1)}{(w_{1,N} - HOLD)}$;

Step19 Set $TK1 = TK2$;
 $TK2 = TK$;
 $k = k + 1$.

Step20 OUTPUT ("Maximum number of iterations exceeded");
STOP.

[Comment](#)

Step 5 of 22

(b)

4(a)

Write the Nonlinear boundary value Problem $y'' = y^3 - yy'$, $1 \leq x \leq 2$ with boundary conditions $y(1) = 1/2$ and $y(2) = 1/3$.

This is of the form $y'' = f(x, y, y')$ for $a \leq x \leq b$ with $y(a) = \alpha$ and $y'(a) = t$.

Choose the parameter $t = t_i$ such that $\lim_{t \rightarrow 0} y(b, t_i) = y(b) = \beta$ where $y(x, t_i)$ denotes the solution to the initial value problem involving a parameter t with $t = t_i$ and $y(x)$ denotes the solution to a nonlinear boundary value problem.

The actual solution is $y(x) = (1 + x)^{-1}$.

Choose $h = 0.1$, then $N = 10$, $TOL = 10^{-4}$, and $M = 100$.

It is required to approximate solution to the following initial value problem involving a parameter t with $t = t_i$:

$y'' = y^3 - yy'$, $1 \leq x \leq 2$ with boundary conditions $y(1) = 0$ and $y'(1) = t_i$.

$z'' = \left(\frac{\partial f}{\partial y}\right)z + \left(\frac{\partial f}{\partial y'}\right)z'$ for $1 \leq x \leq 2$ with $z(1) = 0$ and $z'(1) = 1$.

$= (3y^2 - y^2)z - yz'$

[Comment](#)

Step 6 of 22

Apply the Non Linear Shooting with SECANT method Algorithm with Maple code as follows:

```
> restart;
> # NONLINEAR SHOOTING WITH SECANT METHOD ALGORITHM
> #
> # To approximate the solution of the nonlinear boundary-value problem
> #
> #  $y'' = F(X,Y,Y')$ ,  $A <= X <= B$ ,  $Y(A) = ALPHA$ ,  $Y(B) = BETA$ :
> #
> # INPUT: Endpoints  $A,B$ ; boundary conditions  $ALPHA, BETA$ ; number of
> # subintervals  $N$ ; tolerance  $TOL$ ; maximum number of iterations  $M$ .
> #
> # OUTPUT: Approximations  $W(I,J)$  TO  $Y(X)$ ;  $W(2,I)$  TO  $Y'(X)$ 
> # for each  $i=1, \dots, N$  or a message that the maximum
> # number of iterations was exceeded.
```

[Comment](#)

Step 7 of 22

Continuation of the above **maple code**:

```
> print('This is the Nonlinear Shooting with Newton's Method. ');
> print('Input the function F(X,Y,Z) in terms of x, y, z. ');
> F := scanf('%s')[1]; print('F(x,y,z) = '); print(F);
> FY := diff(F, y);
> FYP := diff(F, z);
> F := unapply(F, x, y, z);
> FY := unapply(FY, x, y, z);
> FYP := unapply(FYP, x, y, z);
> OK := FALSE;
> while OK = FALSE do
> print('Input left and right endpoints separated by blank. ');
```

[Comment](#)

Step 8 of 22

Continuation of the above **maple code**:

```
> A := scanf('%e')[1]; print('Left endpoint = '); print(A);
> B := scanf('%e')[1]; print('Right endpoint = '); print(B);
> if A >= B then
> print('Left endpoint must be less than right endpoint. ');
> else OK := TRUE;
> fi;
> ed;
> print('Input Y(A). ');
> ALPHA := scanf('%e')[1]; print('alpha = '); print(ALPHA);
> print('Input Y(B). ');
> BETA := scanf('%e')[1]; print('beta = '); print(BETA);
> TK := (BETA - ALPHA)/(B - A);
> print('TK = '); print(TK);
> print('Input new TK. Enter 1 for yes or 2 for no. ');
> NAME := scanf('%d')[1]; print('Input is '); print(AA);
> if AA = 1 then
> print('Input new TK. ');
> TK := scanf('%g')[1]; print('New TK = '); print(TK);
```

Continuation of the above **maple code**:

```
> fi;
> OK := FALSE;
> while OK = FALSE do
> print('Input an integer > 1 for the number of subintervals. ');
> N := scanf('%d')[1]; print('n = '); print(N);
> if N < 1 then
> print('Number must exceed 1. ');
> else
> OK := TRUE;
> fi;
> ed;
> OK := FALSE;
> while OK = FALSE do
```

[Comment](#)

Step 9 of 22

Continuation of the above **maple code**:

```
> print('Input Tolerance. ');
> TOL := scanf('%g')[1]; print('Tolerance = '); print(TOL);
> if TOL <= 0 then
> print('Tolerance must be positive. ');
> else
> OK := TRUE;
> fi;
> ed;
> OK := FALSE;
> while OK = FALSE do
> print('Input maximum number of iterations. ');
> NN := scanf('%d')[1]; print('Maximum number of iterations = '); print(NN);
> if NN <= 0 then
> print('Must be positive integer. ');
> else
> OK := TRUE;
> fi;
> ed;
```

[Comment](#)

Step 10 of 22

Continuation of the above **maple code**:

```
> if OK = TRUE then
> print('Choice of output method. ');
> print('1. Output to screen. ');
> print('2. Output to text file. ');
> print('Please enter 1 or 2. ');
> FLAG := scanf('%d')[1]; print('Input is '); print(FLAG);
> if FLAG = 2 then
> print('Input the file name in the form - drive:\name.ext ');
> print('For example A:\OUTPUT.DTA. ');
> NAME := scanf('%s')[1]; print('Output file is '); print(NAME);
> OUP := fopen(NAME, WRITE, TEXT);
> else
> OUP := default;
> fi;
> fprint(OUTP, 'NONLINEAR SHOOTING WITH SECANT METHOD n/n ');
> fprint(OUTP, ' I X(t) W1(t) W2(t)n ');
```

[Comment](#)

Step 11 of 22

Continuation of the above **maple code**:

```
> # Step 1
> H := (B - A)/N;
> K := 2;
> # TK is already computed.
> OK := FALSE;
> # Step 2
> while K <= NN and OK = FALSE do
> # Step 3
> W[0] := ALPHA;
> W[0] := TK;
> U[1] := 0;
> U[2] := 1;
> # Step 4
> # Runge-Kutta method for systems is used in Steps 5 and 6
> for I2 from 1 to N do
> # Step 5
> X := A + (I2 - 1)*H;
> T := X + 0.5*H;
```

[Comment](#)

Step 12 of 22

Continuation of the above **maple code**:

```
> # Step 6
> K[1] := H*W[I2-1];
> K[2] := H*F(X, W[I2-1], W[I2-1]);
> K[21] := H*W[I2-1] + 0.5*K[2];
> K[22] := H*F(X, W[I2-1] + 0.5*K[21], W[I2-1] + 0.5*K[2]);
> K[3] := H*W[I2-1] + 0.5*K[22];
> K[32] := H*F(X, W[I2-1] + 0.5*K[21], W[I2-1] + 0.5*K[22]);
> K[4] := H*W[I2-1] + K[32];
> K[42] := H*F(X + H, W[I2-1] + K[31], W[I2-1] + K[32]);
> W[I2] := W[I2-1] + (K[1] + 2*(K[2] + K[3]) + K[4])/6;
> W[2][I2] := W[2][I2-1] + (K[12] + 2*(K[22] + K[32] + K[42])/6;
> # Step 7
> # Test for accuracy
> if abs(W[1][N] - BETA) ( TOL then
) # Step 8
> I2 := 0;
> fprint(OUTP, '%3d %13.8f %13.8f %13.8f\n', I2, A, ALPHA, TK);
> for I2 from 1 to N do
> I := I2 + 1;
> X := A + I2*H;
> fprint(OUTP, '%3d %13.8f %13.8f %13.8f\n', I2, X, W[I-1], W[2][I-1]);
> ed;
> fprint(OUTP, 'Convergence in %d iterations\n', K);
> fprint(OUTP, 't = %4.7e\n', TK);
```

[Comment](#)

Step 13 of 22

Continuation of the above **maple code**:

```
> # Step 7
> # Test for accuracy
> if abs(W[1][N] - BETA) ( TOL then
) # Step 8
> I2 := 0;
> fprint(OUTP, '%3d %13.8f %13.8f %13.8f\n', I2, A, ALPHA, TK);
> for I2 from 1 to N do
> I := I2 + 1;
> X := A + I2*H;
> fprint(OUTP, '%3d %13.8f %13.8f %13.8f\n', I2, X, W[I-1], W[2][I-1]);
> ed;
> fprint(OUTP, 'Convergence in %d iterations\n', K);
> fprint(OUTP, 't = %4.7e\n', TK);
```

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